

1) $3 \frac{d^2 y}{dt^2} + 6 \frac{dy}{dt} + 9y = 0$ is equivalent to

$$\frac{d^2 y}{dt^2} + 2 \frac{dy}{dt} + 3y = 0$$

To convert, set $v = \frac{dy}{dt}$, so that we have (by differentiating) $\frac{dv}{dt} = \frac{d^2 y}{dt^2}$.

An equivalent first order system is

$$\begin{cases} \frac{dy}{dt} = v \\ \frac{dv}{dt} = -2v - 3y \end{cases}$$

or, with $\underline{Y}(t) = \begin{pmatrix} y(t) \\ v(t) \end{pmatrix}$, the equivalent system can be written

$$\frac{d\underline{Y}}{dt} = \underline{A} \underline{Y} \quad \text{with} \quad \underline{A} = \begin{pmatrix} 0 & 1 \\ -3 & -2 \end{pmatrix}$$

2) e-values of $\underline{A} = \begin{pmatrix} -2 & -2 \\ -2 & 1 \end{pmatrix}$:

$$\det(\underline{A} - \lambda \underline{I}) = \det \begin{pmatrix} -2-\lambda & -2 \\ -2 & 1-\lambda \end{pmatrix}$$

$$= (-2-\lambda)(1-\lambda) - 4 = (-2+2\lambda-\lambda+\lambda^2) - 4$$

$$= \lambda^2 + \lambda - 6 = (\lambda+3)(\lambda-2)$$

e-values are the solutions (roots) of

$$(\lambda+3)(\lambda-2) = 0,$$

namely, $\lambda_1 = -3$ and $\lambda_2 = 2$.

e-vectors :

$$\text{for } \lambda_1 = -3, \quad A\vec{v}_1 = \lambda_1\vec{v}_1 \quad \text{or} \quad (A - \lambda_1 I)\vec{v}_1 = \vec{0}$$

$$\Leftrightarrow \left(\begin{pmatrix} -2 & -2 \\ -2 & 1 \end{pmatrix} - (-3) \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \right) \begin{pmatrix} x_1 \\ y_1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Leftrightarrow \begin{pmatrix} -2+3 & -2 \\ -2 & 1+3 \end{pmatrix} \begin{pmatrix} x_1 \\ y_1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Leftrightarrow \begin{pmatrix} 1 & -2 \\ -2 & 4 \end{pmatrix} \begin{pmatrix} x_1 \\ y_1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Leftrightarrow \begin{cases} x_1 - 2y_1 = 0 \\ -2x_1 + 4y_1 = 0 \end{cases} \Leftrightarrow \begin{cases} x_1 = 2y_1 \\ \text{(or } y_1 = \frac{1}{2}x_1) \end{cases}$$

$$\text{e.g., } \vec{v}_1 = \begin{pmatrix} 2 \\ 1 \end{pmatrix}.$$

$$\text{For } \lambda_2 = 2, \quad A\vec{v}_2 = \lambda_2\vec{v}_2 \quad \text{or} \quad (A - \lambda_2 I)\vec{v}_2 = \vec{0}$$

$$\Leftrightarrow \left(\begin{pmatrix} -2 & -2 \\ -2 & 1 \end{pmatrix} - 2 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \right) \begin{pmatrix} x_2 \\ y_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Leftrightarrow \begin{pmatrix} -2-2 & -2 \\ -2 & 1-2 \end{pmatrix} \begin{pmatrix} x_2 \\ y_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Leftrightarrow \begin{pmatrix} -4 & -2 \\ -2 & -1 \end{pmatrix} \begin{pmatrix} x_2 \\ y_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Leftrightarrow \begin{cases} -4x_2 - 2y_2 = 0 \\ -2x_2 - y_2 = 0 \end{cases} \Leftrightarrow -2x_2 = y_2$$

$$\text{e.g., } \vec{v}_2 = \begin{pmatrix} 1 \\ -2 \end{pmatrix}.$$

$$\therefore \boxed{\vec{Y}(t) = k_1 e^{-3t} \begin{pmatrix} 2 \\ 1 \end{pmatrix} + k_2 e^{2t} \begin{pmatrix} 1 \\ -2 \end{pmatrix}} \\ \text{is the general solution.}$$

3) A good guess is $y(t) = e^{at}$ for some suitable constant a . To find all suitable values for the variable (or parameter) a we substitute e^{at} for $y(t)$ in the differential equation to get

$$2a^2 e^{at} + 7a e^{at} + 3e^{at} = 0 \quad (1)$$

(since $\frac{dy}{dt} = \frac{d}{dt} e^{at} = a e^{at}$)

Factor out e^{at} , which is never zero:

$$2a^2 + 7a + 3 = 0 \quad (2)$$

Solve equation (2) to get

$$a = \frac{-7 \pm \sqrt{49 - 24}}{4} = \frac{-7 \pm \sqrt{25}}{4} = \frac{-7 \pm 5}{4}$$

$$\Rightarrow a \in \{a_1, a_2\} \text{ where } \begin{cases} a_1 = \frac{-7+5}{4} = -\frac{2}{4} = -\frac{1}{2} \\ a_2 = \frac{-7-5}{4} = -\frac{12}{4} = -3 \end{cases}$$

giving solutions

$$y_1(t) = e^{-\frac{1}{2}t} \quad \text{and} \quad y_2(t) = e^{-3t}$$

for the differential equation.

4) (i) $\frac{dx}{dt} = 10x \left(1 - \frac{x}{10}\right) - 20xy$

$$\frac{dy}{dt} = -5y + \frac{xy}{20}$$

(ii) $\frac{dx}{dt} = 0.3x - \frac{xy}{100}$

$$\frac{dy}{dt} = 15y \left(1 - \frac{y}{15}\right) + 25xy$$

Equilibrium Points?

Solve

$$\begin{aligned} 10x - x^2 - 20xy &= 0 \\ -5y + \frac{xy}{20} &= 0 \end{aligned}$$

Solve

$$\begin{aligned} 0.3x - \frac{xy}{100} &= 0 \\ 15y \left(1 - \frac{y}{15}\right) + 25xy &= 0 \end{aligned}$$

4) continued -

(i) Equivalently, we have

$$(10 - x - 20y)x = 0$$

$$\left(-5 + \frac{x}{20}\right)y = 0$$

That is, we have equations of the form $AB=0$ and $CD=0$, so solutions ought to arise from

setting $A=0$ and $C=0$,

$A=0$ and $D=0$,

$B=0$ and $C=0$,

$B=0$ and $D=0$.

- If we set $10 - x - 20y = 0 = -5 + \frac{x}{20}$, then $x=100$ and $y = \frac{10-x}{20} = \frac{-90}{20} = -\frac{9}{2}$, i.e., $(x, y) = (100, -9/2)$.
- If we set $10 - x - 20y = 0$ and $y=0$, then $x=10$, and $(x, y) = (10, 0)$.
- If we set $x=0$ and $-5 + \frac{x}{20} = 0$ we have a contradiction.
- If we set $x=0$ and $y=0$, we have equilibrium solution $(x, y) = (0, 0)$.

4) continued -

$$(ii) \begin{cases} 0.3x - \frac{xy}{100} = 0 \iff (0.3 - \frac{y}{100})x = 0 \\ 15y(1 - \frac{y}{15}) + 25xy = 0 \iff (15 - y + 25x)y = 0 \end{cases}$$

$$\bullet \begin{cases} 0.3 - \frac{y}{100} = 0 \\ 15 - y + 25x = 0 \end{cases} \Rightarrow y = 30, x = \frac{15}{25} = \frac{3}{5} \Rightarrow$$

$$\boxed{(x, y) = (\frac{3}{5}, 30)}$$

$$\bullet \begin{cases} 0.3 - \frac{y}{100} = 0 \\ y = 0 \end{cases} \text{ gives a contradiction}$$

$$\bullet \begin{cases} x = 0 \\ 15 - y + 25x = 0 \end{cases} \Rightarrow y = 15 \Rightarrow \boxed{(x, y) = (0, 15)}$$

$$\bullet \begin{cases} x = 0 \\ y = 0 \end{cases} \Rightarrow \boxed{(x, y) = (0, 0)}$$

There is no significance for $(100, -\frac{1}{2})$ in (i).
 For $(x, y) = (10, 0)$ there are prey but no predators. For $(x, y) = (0, 0)$ there neither prey nor predators

In (ii), for $(0, 15)$ there are predators but the prey is extinct. For $(x, y) = (\frac{3}{5}, 30)$, predators and prey coexist. For $(x, y) = (0, 0)$ there are neither predators nor prey.

5) (Sec. 2.1 #20) $\frac{d^2 y}{dt^2} + \frac{k}{m} y = 0$ (*)

(a) $y(t) = \cos \beta t$. When is this a solution?

Substitute $\cos \beta t$ into (*)

$$\begin{aligned} 0 &= \frac{d^2 y}{dt^2} + \frac{k}{m} y = \frac{d^2}{dt^2} (\cos \beta t) + \frac{k}{m} \cos \beta t \\ &= -\beta^2 \cos \beta t + \frac{k}{m} \cos \beta t \\ &= \left(\frac{k}{m} - \beta^2 \right) \cos \beta t. \end{aligned}$$

In order for $y(t) = \cos \beta t$ to be a solution of (*) we require $\frac{k}{m} - \beta^2 = 0$, so

$$\beta = \pm \sqrt{\frac{k}{m}}$$

(b) What initial condition ($t=0$) in the yv -plane corresponds to this solution?

First, notice that $v = \frac{dy}{dt} = \frac{d}{dt} \cos \beta t$,
so we have $v = -\beta \sin \beta t$.

The system

$$\frac{dy}{dt} = v$$

$$\frac{dv}{dt} = -\frac{k}{m} y$$

has solution $\begin{pmatrix} y \\ v \end{pmatrix} = \begin{pmatrix} \cos \beta t \\ -\beta \sin \beta t \end{pmatrix}$

corresponding to $y(t)$, and at $t=0$

$$\begin{pmatrix} y(0) \\ v(0) \end{pmatrix} = \begin{pmatrix} \cos 0 \\ -\beta \sin 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

so $\boxed{y(0) = 1 \text{ and } v(0) = 0}$.

5) continued —

(c) In terms of k and m , what is the period of this solution?

The period of a function $f(t)$ is the smallest positive number p such that $f(t+p) = f(t)$ for every t .

The solution $y(t) = \cos \beta t = \cos \sqrt{\frac{k}{m}} t$ has period $\boxed{2\pi / \sqrt{k/m} = 2\pi \sqrt{m/k}}$.

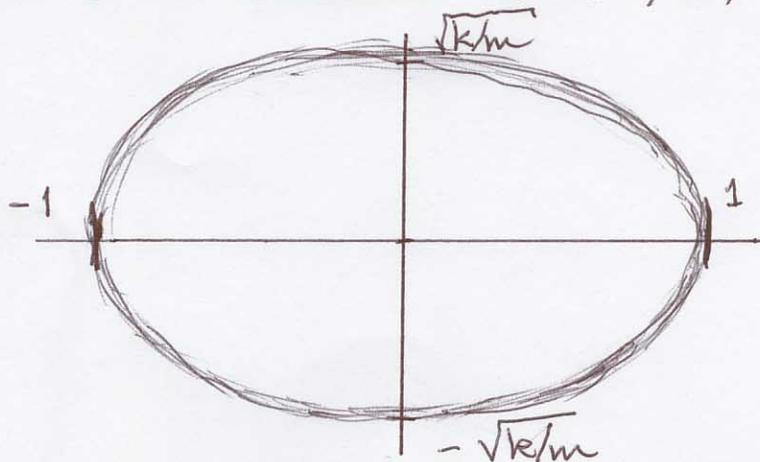
(d) Sketch the solution curve (in the yv -plane) associated to the solution $y(t)$ [Hint: consider the quantity $y^2 + (v/\beta)^2$].

We observe that $y^2 + (v/\beta)^2$

$$= \cos^2 \beta t + (-\beta \sin(\beta t) / \beta)^2$$

$$= \cos^2 \beta t + \sin^2 \beta t = 1,$$

so (y, v) moves along an ellipse centered at $(0, 0)$



6) §2.2 #12-16

(#12) The system
$$\begin{cases} \frac{dR}{dt} = 2R(1 - \frac{R}{2}) - 1.2RF \\ \frac{dF}{dt} = -F + 0.9RF, \end{cases}$$

has equilibrium solutions for which

$$\begin{cases} 2R(1 - \frac{R}{2}) - 1.2RF = 0 \\ -F + 0.9RF = 0 \end{cases}$$

The bottom equation holds true if $F=0$
 or if $R = \frac{10}{9}$ (since $-F + 0.9RF = -F(1 - 0.9R)$)

Let's deal separately with these cases:

(i) $F=0$. Then the top equation,

$$2R(1 - \frac{R}{2}) - 1.2RF = 0$$

simplifies to

$$2R(1 - \frac{R}{2}) = 0,$$

so it holds iff $R=0$ or $R=2$.

We thus find two equilibrium solutions

$$\boxed{(R, F) = (0, 0)} \text{ and } \boxed{(R, F) = (2, 0)}.$$

(ii) $R = \frac{10}{9}$. Then the top equation

$$2R(1 - \frac{R}{2}) - 1.2RF = 0$$

simplifies to

$$2(1 - \frac{10/9}{2}) - 1.2F = 0; \quad \text{i.e.,}$$

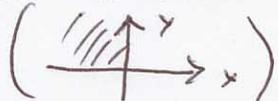
$$\frac{8}{9} - \frac{6}{5}F = 0; \quad \text{so}$$

$$F = \frac{40}{54} = \frac{20}{27}; \quad \boxed{(R, F) = (\frac{10}{9}, \frac{20}{27})}$$

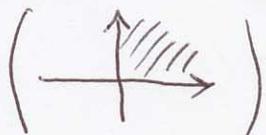
6) #14 Continued —

Graphs are not periodic.

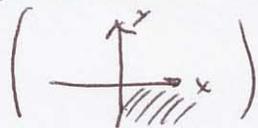
- (i) Value of $x(t)$ starts negative
Value of $y(t)$ starts positive
∴ solution starts in the 2nd quadrant



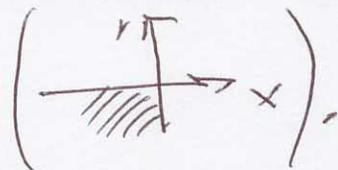
- (ii) For an interval of time, both $x(t)$ and $y(t)$ are positive, so the solution curve moves into the first quadrant



- (iii) Next, $y(t)$ becomes negative, so the solution curve enters the 4th quadrant

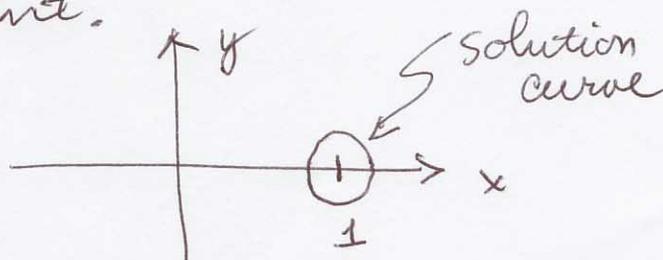


- (iv) Finally, $x(t)$ becomes negative, so the solution curve enters the 3rd quadrant



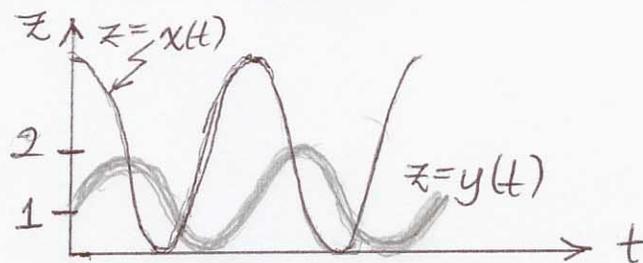
#16

$x(t)$, $y(t)$ both periodic, so the solution curve returns to its starting point.

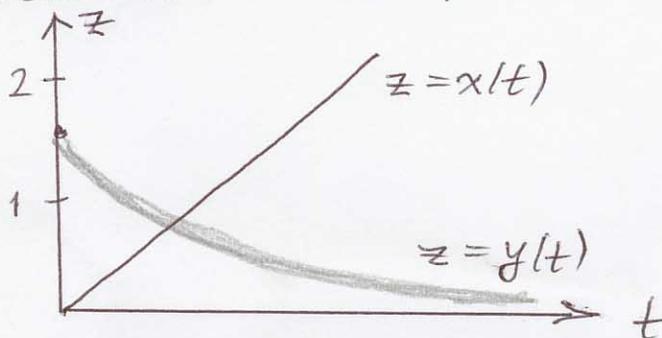


7) Sec. 2.2 # 23-26

(#24) Solution curve is an ellipse centered at $(2, 1)$, so the $x(t)$ -graph is periodic, oscillates about the line $x=2$, and the $y(t)$ -graph is periodic, oscillates about the line $y=1$



(#26) The $x(t)$ -graph starts with a small positive value and increases (monotonically) with t . The $y(t)$ -graph starts with value around 1.6 and decreases as t increases. One possible sketch-



8) §2.4 #2(a, b) $\frac{dx}{dt} = 2x$

$$\frac{dy}{dt} = y$$

(a) Check that $\underline{Y(t)} = \begin{pmatrix} e^{2t} \\ 3e^t \end{pmatrix}$ is a solution.

We compute

$$\frac{dx}{dt} = \frac{d}{dt} (e^{2t}) = 2e^{2t} = 2x, \text{ so the top}$$

8) continued —

equation is satisfied. We also compute

$$\frac{dy}{dt} = \frac{d}{dt}(3e^t) = 3e^t = y,$$

so the bottom equation is also satisfied.

∴ $\tilde{y}(t) = \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} e^{2t} \\ 3e^t \end{pmatrix}$ is a solution. // (a)

(b), (c) — See Homework #10.

Problems 9 through 14 are answered in your textbook (at the back)